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EFFECTFUL TRANSITION SYSTEMS

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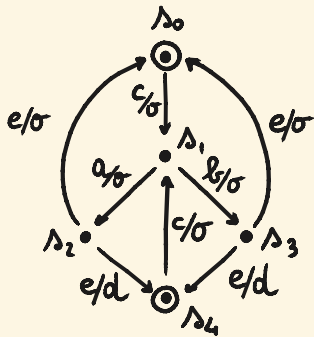
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OVERVIEW

- effectful transition systems
- bisimulation
- trace equivalence

CLASSICAL TRANSITION SYSTEMS

A transition system with state space S , inputs A and outputs B is a relation $f \subseteq S \times A \times S \times B$ with a set $S_0 \subseteq S$ of initial states.



$$S = \{s_0, s_1, s_2, s_3, s_4\}$$

$$A = \{a, b, c, e\}$$

$$B = \{d, \sigma\}$$

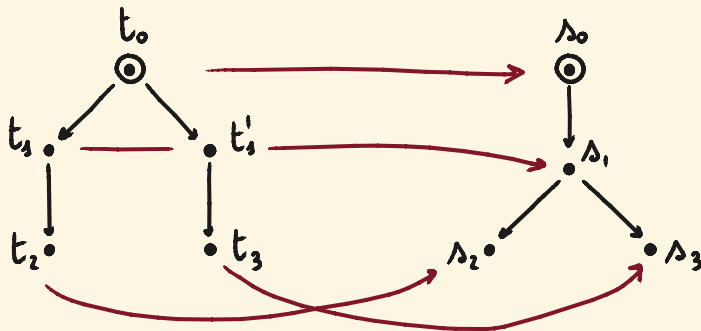
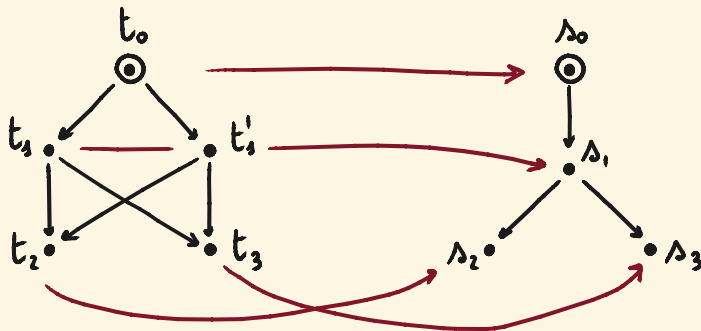
$$S_0 = \{s_0, s_4\}$$

MORPHISMS OF TRANSITION SYSTEMS

A morphism of transition systems $u: (f, S, S_0) \rightarrow (g, T, T_0)$ is a function $u: S \rightarrow T$ such that

- for all $s, s' \in S, a \in A, b \in B$
if $(s, a, s', b) \in f$, then $(u(s), a, u(s'), b) \in g$, and,
- for all $s \in S, a \in A, b \in B, t \in T$
if $(u(s), a, t, b) \in g$, then there is $s' \in S$ with
 $(s, a, s', b) \in f$ and $u(s') = t$
- for all $t \in T_0$ there is $s \in S_0$ with $u(s) = t$

MORPHISMS - EXAMPLE

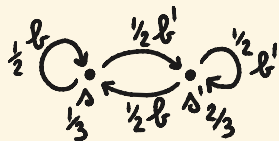


PROBABILISTIC TRANSITION SYSTEMS

A probabilistic transition system with state space S , inputs A and outputs B is a stochastic channel

$f: S \times A \rightarrow S \times B$ with an initial distribution ν_0 on S :

- a function $f: S \times A \times S \times B \rightarrow [0, 1]$ such that $\{(s', b) \mid f(s, a, s', b) > 0\}$ is finite and $\sum_{s', b} f(s, a, s', b) = 1$
- a function $\nu_0: S \rightarrow [0, 1]$ such that $\{s \mid \nu_0(s) > 0\}$ is finite and $\sum_S \nu_0(s) = 1$



$$S = \{s, s'\}$$

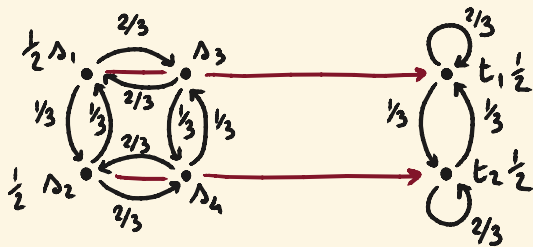
$$A = \{*\}$$

$$B = \{b, b'\}$$

MORPHISMS OF PROBABILISTIC TRANSITION SYSTEMS

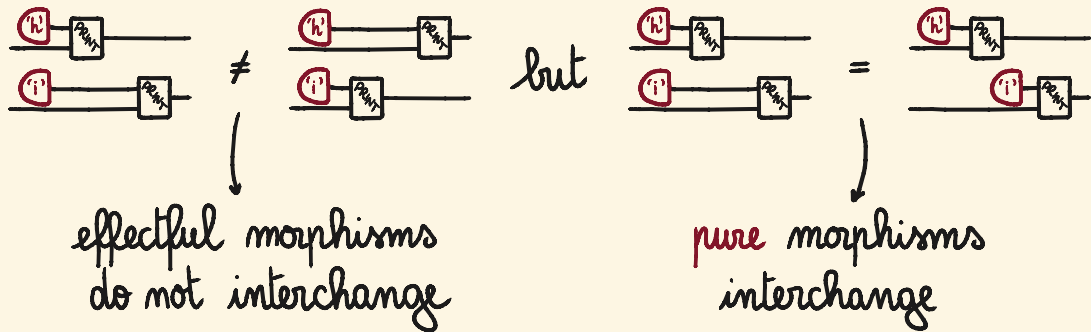
A morphism of transition systems $u: (f, S, s_0) \rightarrow (g, T, t_0)$ is a function $u: S \rightarrow T$ such that

- $\sum_{\substack{s' \\ u(s')=t'}} f(s', b | s, a) = g(t', b | u(s), a)$
- $\sum_{\substack{t \\ u(s)=t}} s_0(s) = t_0(t)$



EFFECTFUL CATEGORIES

An *effectful category* $(\mathcal{V}, \mathcal{L})$ is an identity on objects monoidal functor $V: \mathcal{V} \rightarrow \mathcal{Z}(\mathcal{L})$ from a monoidal category \mathcal{V} to the centre $\mathcal{Z}(\mathcal{L})$ of a premonoidal category \mathcal{L} .



[Levy 2004, Román 2022]

EFFECTFUL TRANSITION SYSTEMS

\mathcal{C} effectful category over Set

A transition system $(f, S, s_0): A \rightarrow B$ in \mathcal{C} with state space S , inputs A and outputs B is a morphism

$$f: S \otimes A \rightarrow S \otimes B \quad \begin{array}{c} S \\ \text{---} \square \text{---} \\ A \quad \delta \quad B \end{array}$$

with an initial state

$$s_0: I \rightarrow S \quad \begin{array}{c} \text{---} \square \text{---} \\ \text{---} \end{array} S$$

A morphism of transition systems $u: (f, S, s_0) \rightarrow (g, T, t_0)$ is a function $u: S \rightarrow T$ such that

$$\begin{array}{c} S \\ \text{---} \square \text{---} \\ A \quad \delta \quad B \end{array} \begin{array}{c} \text{---} \square \text{---} \\ \text{---} \end{array} T = \begin{array}{c} S \\ \text{---} \square \text{---} \\ A \quad \delta \quad B \end{array} \begin{array}{c} \text{---} \square \text{---} \\ \text{---} \end{array} T$$

$$\begin{array}{c} \text{---} \square \text{---} \\ \text{---} \end{array} S \begin{array}{c} \text{---} \square \text{---} \\ \text{---} \end{array} T = \begin{array}{c} \text{---} \square \text{---} \\ \text{---} \end{array} T$$

[cf. Katis, Sabadini, Walters 1997]

EFFECTFUL TRANSITION SYSTEMS - EXAMPLES

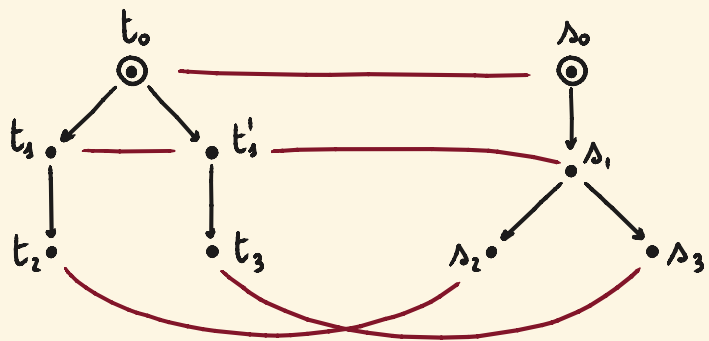
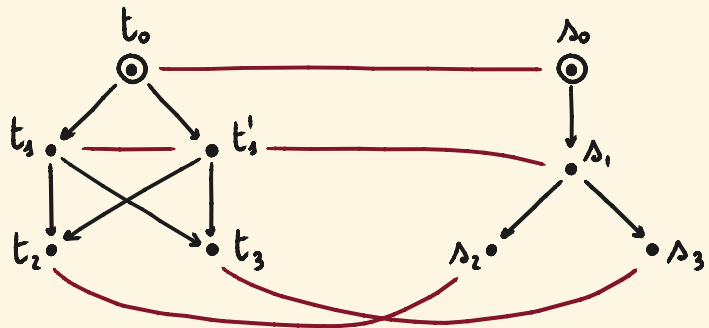
- $\mathcal{L} = \text{Rel}$
⇒ classical transition systems and their morphisms
- $\mathcal{L} = \text{Kl}(\mathcal{D})$
⇒ probabilistic transition systems and their morphisms

BISIMULATION

Two transition systems (f, S, S_0) and (g, T, T_0) are bisimilar if there is a relation $R \subseteq S \times T$ such that

- for all $s, s' \in S$, $t \in T$, $a \in A$, $b \in B$
 - if $(s, t) \in R$ and $(s, a, s', b) \in f$, then there is $t' \in T$ with $(s', t') \in R$ and $(t, a, t', b) \in g$
 - if $s' \in S_0$, then there is $t' \in T_0$ with $(s', t') \in R$
- for all $s \in S$, $t, t' \in T$, $a \in A$, $b \in B$
 - if $(s, t) \in R$ and $(t, a, t', b) \in g$, then there is $s' \in S$ with $(s', t') \in R$ and $(s, a, s', b) \in f$
 - if $t' \in T_0$, then there is $s' \in S_0$ with $(s', t') \in R$

BISIMULATION - EXAMPLE



CHARACTERISING BISIMULATION

PROPOSITION (Rutten, 1995)

Two transition systems (f, S, S_0) and (g, T, T_0) are bisimilar
iff there is a span $(f, S, S_0) \xleftarrow{u} (h, R, R_0) \xrightarrow{v} (g, T, T_0)$
of morphisms of transition systems.

\rightsquigarrow R is a bisimulation and u, v are projections

PROBABILISTIC BISIMULATION

Two transition systems (f, S, s_0) and (g, T, t_0) are bisimilar if there is a relation $R \subseteq S \times T$ such that

- for all $s \in S, t \in T, a \in A, b \in B, X$ equivalence class

$$\text{if } (s, t) \in R \quad \sum_{s' \in X \cap S} f(s', b | s, a) = \sum_{t' \in X \cap T} g(t', b | t, a)$$

- for all equivalence classes X

$$\sum_{s \in X \cap S} s_0(s) = \sum_{t \in X \cap T} t_0(t)$$

[Blute, Desharnais, Edalat, Panangaden 1997]

EFFECTFUL BISIMULATION

Two effectful transition systems $(f, S), (g, T) : A \rightarrow B$ are bisimilar if they are connected by spans of morphisms:

$$(f, S) \xleftarrow{(h_1, R_1)} (f_1, S_1) \xleftarrow{(h_2, R_2)} \dots \xleftarrow{(h_m, R_m)} (g, T)$$

PROPOSITION

When $\mathcal{C} = \text{Kl}(M)$, then (f, S) and (g, T) are bisimilar iff they have the same bisimulation quotient, i.e.

there is (h, Q) with morphisms $(f, S) \xrightarrow{r} (h, Q) \xleftarrow{q} (g, T)$.

EFFECTFUL BISIMULATION - EXAMPLES

- $\mathcal{L} = \text{Rel}$
⇒ classical bisimulation
- $\mathcal{L} = \text{Kl}(\mathcal{D})$
⇒ probabilistic bisimulation

EXECUTION TRACES

A trace of a transition system (\mathcal{J}, S, S_0) relative to a sequence (a_0, a_1, \dots) of inputs is a sequence (b_0, b_1, \dots) of outputs that has a sequence (s_0, s_1, \dots) of states generating it:

- $s_0 \in S_0$
- for all n , $(s_n, a_n, s_{n+1}, b_n) \in \mathcal{J}$

Two transition systems are trace equivalent if, for all sequences of inputs, their traces coincide.

PROBABILISTIC EXECUTION TRACES

A trace of a transition system (f, S, s_0) relative to a sequence (a_0, a_1, \dots) of inputs is a sequence (d_0, d_1, \dots) of distributions d_m on B^{m+1}

- $f_0(s', b_0) = \sum_{s \in S} f(s', b_0 | s, a_0) \cdot s_0(s)$
- $f_{m+1}(s', b_{m+1}, \dots, b_0) = \sum_{s \in S} f(s', b_{m+1} | s, a_{m+1}) \cdot f_m(s, b_m, \dots, b_0)$
and $d_m(b_{m+1}, \dots, b_0) = \sum_s f_m(s, b_{m+1}, \dots, b_0)$

Two transition systems are trace equivalent if, for all sequences of inputs, their traces coincide.

[Blute, Desharnais, Edalat, Panangaden 1997]

EFFECTFUL STREAMS

An effectful stream $F: A \rightarrow B$ with inputs $A = (A_0, A_1, \dots)$ and outputs $B = (B_0, B_1, \dots)$ is

- a memory $M_F \in \text{obj } \mathcal{C}$
- a first action $\text{now}(F): A_0 \rightarrow M_F \otimes B_0$ in \mathcal{C}
- a rest of the action $\text{later}(F): M_F \cdot A^+ \rightarrow B^+$

quotiented by the equivalence relation generated by

$$F \sim g \text{ if there is a function } u \begin{cases} \text{now } F = \text{now } g; (u \otimes \mathbb{1}) \\ u \cdot \text{later } F \sim \text{later } g \end{cases}$$

EFFECTFUL TRACES

The trace of an effectful transition system (f, S, s_0) is the effectful stream $\text{tr}(f, S, s_0)$ defined coinductively by

- $\text{now}(\text{tr}(f, S, s_0)) := (s_0 \otimes \perp); f$

- $\text{later}(\text{tr}(f, S, s_0)) := (f)$

where (f) is the effectful stream

- $\text{now}(f) := f$

- $\text{later}(f) := (f)$

Two effectful transition systems (f, S, s_0) and (g, T, t_0) are trace equivalent if $\text{tr}(f, S, s_0) = \text{tr}(g, T, t_0)$.

EFFECTFUL TRACES - EXAMPLES

- $\mathcal{L} = \text{Rel}$
⇒ classical trace equivalence
- $\mathcal{L} = \text{Kl}(\mathcal{D})$
⇒ probabilistic trace equivalence

BISIMULATION \Rightarrow TRACE EQUIVALENCE

PROPOSITION

If two effectful transition systems are bisimilar, then they are trace equivalent.

PROOF SKETCH

$$u : (f, S, s_0) \rightarrow (g, T, t_0)$$

$$\begin{aligned}\Rightarrow \text{now } \text{tr}(g, T, t_0) &= (t_0 \otimes \perp); g \\ &= ((s_0; u) \otimes \perp); g \\ &= (s_0 \otimes \perp); f; (u \otimes \perp) \\ &= \text{now } \text{tr}(f, S, s_0); (u \otimes \perp)\end{aligned}$$

by coinduction, $u \cdot \text{later } \text{tr}(g, T, t_0) \sim \text{later } \text{tr}(f, S, s_0)$ \square

CONCLUSIONS & FUTURE WORK

- transition systems, bisimulation and trace equivalence in effectful categories
- premonoidal examples
- internal language of premonoidal categories
- string diagrams in $\mathcal{St} \mathcal{C}$ are sound for bisimulation, can we get completeness?

$$\begin{array}{c} \text{---} \square \delta \text{---} \\ \text{---} \square \gamma \text{---} \end{array} = \begin{array}{c} \text{---} \square \delta \text{---} \\ \text{---} \square \gamma \text{---} \end{array} \Rightarrow \begin{array}{c} \text{---} \square \delta \text{---} \\ \text{---} \square \gamma \text{---} \end{array} \approx \begin{array}{c} \text{---} \square \delta \text{---} \\ \text{---} \square \gamma \text{---} \end{array}$$

↕